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Comment on "Faraday waves in a Hele-Shaw cell" [Phys. Fluids 30, 042106 (2018)] FREE

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We propose improved dimensionless variables and scaling law to describe the height of Faraday waves in a vertically vibrating Hele–Shaw cell. In comparison with those suggested by Li *et al.*,¹ the influence of the liquid depth *d* on the wave height *H* is disregarded, and the critical acceleration F_c , at which the Faraday instability is triggered, is now taken into account. We support our approach with results from an additional set of experimental data, which includes the measurement of F_c and encompasses the parameter range studied by Li *et al.*¹ Our proposal is based on the following arguments.

(1) The term tanh(kd) (here $k = \frac{2\pi}{\lambda}$, where λ is the wavelength) controls the crossover from shallow to deep water waves regimes,² becoming asymptotic to unity as d exceeds a certain liquid depth d_{cross} (for fixed λ). In the deep water waves regime, d is large enough, so that the waves do not interact with the bottom of the Hele–Shaw cell, and H and λ become independent of d. Specifically, we understand that this condition is met in the work of Li *et al.*¹ (for which $d \ge 10$ mm). In fact, assuming the crossover occurs as late as $kd \approx 2$ [with tanh(2) = 0.964] and considering that λ ranges from 15 to 25 mm (as reported in Fig. 10 of Li *et al.*¹) then the condition $4.7 \,\mathrm{mm} < d_{cross} < 8 \,\mathrm{mm}$ is satisfied in their work. On the other hand, no consistent increase in H with d can be inferred from Table III of Li *et al.*¹ (for constant f and F). Moreover, it is evident in previous works by some of the same authors', in equal or very similar, experimental conditions (cf. Fig. 5 of Li et al.³ and Fig. 2 of Li et al.⁴). Indeed, in those articles, it is stated that *H* is independent of *d* for $d \ge 10$ mm. Finally, from previous works by other authors, which employed a cell gap of 1.87 mm (instead of 1.7 mm from Li *et al.*¹) and for f = 24 Hz, it was shown how *H* and λ became independent of *d* for *d* ~ 6 mm (cf. Fig. 5 of Martino *et al.*⁵ and Fig. 6.12 from Barba-Maggi⁶).

We conclude that, in the work of Li *et al.*,¹ *H* is independent of *d*, and then, it is not correct to include *d* in the dimensionless variables (and scaling law) for *H*.

(2) As Faraday waves are only triggered if the vibration acceleration F exceeds a critical value F_c and vanish for $F < F_c$, their amplitude is more likely to be controlled by a reduced parameter $(F - F_c)$ than simply by F. This parameter was used by Perinet *et al.*⁷ to study the amplitude of Faraday waves and by other authors^{8.9} to study the transition from order to disorder in Faraday wave patterns.

In view of these arguments, we propose a scaling law with two dimensionless variables, Π_1 and Π_2 , four independent variables, *H*, *f*, *g*, and $(F - F_c)$, and two independent physical dimensions, *L* and *T*, as follows:

$$\Pi_1 = \frac{Hf^2}{g}, \quad \Pi_2 = \frac{F - F_c}{g},\tag{1}$$

$$\Pi_1 = \Phi(\Pi_2) \Rightarrow \frac{Hf^2}{g} = \Phi\left[\frac{F - F_c}{g}\right].$$
 (2)

To compare both approaches, we have performed experiments for f = 16, 20, 25, 30, and 35 Hz, replicating the liquid depths explored by Li *et al.*¹ (d = 10, 20, and 30 mm). The Hele–Shaw cell used is reported in Martino et al.,5 while all other experimental conditions reproduced those of Li et al.¹ The experimental procedure was the following: the value of F was increased gradually from F = 0 (flat free surface) up to the stationary waves regime, which is triggered at a first critical value $F = F_c^+$. At this point, H increases sharply from zero to a finite value. We continue increasing *F* in steps of 0.1 m/s^2 , letting the system stabilize for one minute before each measurement of H, up to the non-stationary waves regime. In this regime, the waves are no longer sub-harmonic and do not possess well-defined period, height, or wavelength. We then decrease F down, in steps of 0.1 m/s^2 , until the instability vanishes sharply at $F = F_c(\langle F_c^+)$ (this second critical value is the one reported in our comment¹⁰) and the free surface is again flat. Data points are an average of five measurements for each parameter set. This way of determining F_c is similar to that employed in Rajchenbach *et al.*¹⁰ We refer the reader to that article, and to Perinet *et al.*,⁷ on the

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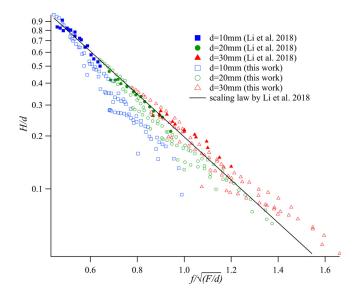


FIG. 1. Data collapse using the dimensionless variables of Li *et al.*¹ (cf. with Fig. 4 from that work). Full symbols correspond to experimental data from Li *et al.*¹ (*f* ranges from 18 to 24 Hz), while hollow symbols represent experimental data from this work (*f* ranges from 16 to 35 Hz). The solid line is the scaling law of Li *et al.*¹

hysteretic behavior of Faraday waves. The acceleration F ranged from 8 to 25 m/s² in our experiments. Note that, as in Li *et al.*,¹ the analysis is restricted to the 2D profiles of the waves.

Figure 1 shows data points from Li *et al.*¹ along with ours, using the dimensionless variables suggested by the former. The solid line is the scaling law of Li *et al.*¹ Note that data points appear dispersed and

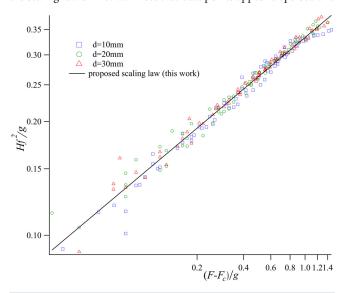


FIG. 2. Data collapse of the dimensionless wave height $\frac{H'_g}{g}$ as a function of reduced acceleration $\frac{(F-F_c)}{g}$ for the experimental data from this work. Each hollow symbol in this figure corresponds to one in Fig. 1; both arise from the same measurement. Note the absence of segregation by the value of *d*. The solid line is a fit by the scaling law $\frac{H'_g}{g} \propto [\frac{F-F_c}{g}]^n$, yielding n = 0.34. Unluckily, F_c was not considered in the work of Li et al., ¹ so we cannot include their data points in this figure.

clearly segregated by the value of *d*, as they do in Fig. 4 of Li *et al.*¹ Those furthest away from the scaling of Li *et al.*¹ correspond to relatively small or large values of *F*. For comparison, a data collapse plot using our dimensionless variables is shown in Fig. 2. Note that the hollow data points in Fig. 2 correspond to the same measurements as those of Fig. 1; however, using our dimensionless variables, they are not segregated by the value of *d*, showing, thus, a good data collapse. Dispersion of data is observed as $\frac{(F-F_c)}{g}$ vanishes. Unluckily, in the work of Li *et al.*¹ F_c was not considered, so we cannot include their data points in Fig. 2. The solid line is a fit by our scaling law, in the form of a power-law function:

$$\frac{Hf^2}{g} \propto \left[\frac{F - F_c}{g}\right]^n. \tag{3}$$

The fit yields a value of n = 0.34. Since Faraday waves belong to the particular class of phenomena, for which an oscillatory instability is triggered only when the critical value of the control parameter is attained,^{11,12} we find that a power-law dependence of H on $(F - F_c)$ is physically meaningful. Note that, in our scaling, H varies inversely with f^2 , as opposed to the scaling of Li *et al.*,¹ for which $\log(H/d) \propto -f$ [Eq. (42) from that work]. In the shallow water regime, our scaling law is likely to be invalid because it does not take into account a possible variation of H with d. The determination of appropriate dimensionless variables and scaling law in the crossover from shallow to deep water waves regimes shall be the subject of further research.

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AUTHOR DECLARATIONS

Conflict of Interest

The authors have no conflicts to disclose.

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